

October 5, 1998

Name _____

Technology used: _____

Textbook/Notes used: _____

Directions: Be sure to include in-line citations, including page numbers if appropriate, every time you use a text or notes or technology. **Only write on one side of each page.**

The Problems

1. Assuming you already know that the reflection, in R^3 , through the plane $y = z$ is a linear transformation. Determine the matrix A of this transformation.
2. Determine if the matrix A below is invertible and, if it is, find its inverse by hand (no technology).

$$\begin{bmatrix} 1 & 1 & 2 \\ 2 & -1 & 1 \\ 2 & 3 & 4 \end{bmatrix}$$

3. Assuming you already know that the reflection, in R^4 (thought of as x, y, z, w -space), through the hyperplane $y = z$ is a linear transformation. Determine the matrix A of this transformation.
4. Give an example of a matrix A such that $\text{image}(A)$ is spanned by the vector $\begin{bmatrix} 2 \\ 7 \end{bmatrix}$.
5. If L is the line in the plane that contains the vector $\begin{bmatrix} 3/5 \\ 4/5 \end{bmatrix}$, find the matrix of the linear transformation that projects a vector \vec{x} onto the line L .

6. If A is an invertible $n \times n$ matrix and B is an $n \times n$ matrix, Is it always the case that

$$(ABA^{-1})^4 = AB^4A^{-1}?$$

7. Let $\vec{v}_1, \vec{v}_2, \vec{v}_3$ be three vectors in R^n . Show that $\text{span}(\vec{v}_1, \vec{v}_2, \vec{v}_3)$ is a subspace of R^n .
8. Find the matrix A of the linear transformation $T : R^2 \rightarrow R^2$ with

$$T \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \end{bmatrix} \quad \text{and} \quad T \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} -2 \\ 3 \end{bmatrix}.$$

9. Suppose a line L in R^3 contains the unit vector $\begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$. Find the matrix of the linear transformation $T(\vec{x}) = \text{proj}_L \vec{x}$ by giving the entries of the matrix A in terms of the components of \vec{u} . What is the sum of the diagonal entries in A ?

10. Let $T : R^n \rightarrow R^m$ be a function and c a scalar. Define a new function $(cT) : R^n \rightarrow R^m$ by

$$(cT)(\vec{x}) = cT(\vec{x}) \quad \text{for all } \vec{x} \text{ in } R^n.$$

Prove that if T is a linear transformation, then so is (cT) .

11. Prove that a function $T : R^n \rightarrow R^m$ is a linear transformation if and only if for all scalars c, d and for all vectors $\vec{v}, \vec{w} \in R^n$ we have $T(c\vec{v} + d\vec{w}) = cT(\vec{v}) + dT(\vec{w})$.

12. Show that it is impossible for a matrix A to have two different inverses. [Hint: Pretend that B, C are distinct inverses and consider the product BAC .]

13. We showed in class that it is impossible to have matrices $A_{3 \times 2}$ and $B_{2 \times 3}$ where the product AB equaled I_3 . On the other hand, it is possible to have such matrices where $BA = I_2$. Give an example of specific matrices A, B satisfying this last equality.

14. Suppose $A_{n \times m}$ and $B_{m \times n}$ are matrices such that $BA = I_m$. Let \vec{b} be a particular vector in R^m . Show that the system of equations $B\vec{x} = \vec{b}$ must be consistent.

15. Is it possible to have an invertible 2×2 matrix A with the property that $A^2 = O_2$? Why or why not? (Here O_2 denotes the 2×2 zero matrix.)

16. Let $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ be some vectors in R^n such that the matrix

$$S = \left[\begin{array}{c|c|c|c} \vec{v}_1 & \vec{v}_2 & \cdots & \vec{v}_n \\ \hline & & & \end{array} \right].$$

is invertible. Let $\vec{w}_1, \vec{w}_2, \dots, \vec{w}_n$ be any vectors in R^m . Use the fact (which you need not prove) that there is a unique linear transformation $T : R^n \rightarrow R^m$ such that $T(\vec{v}_i) = \vec{w}_i$, for all $i = 1, 2, \dots, n$. Find the matrix A of this transformation in terms of S and

$$B = \left[\begin{array}{c|c|c|c} \vec{w}_1 & \vec{w}_2 & \cdots & \vec{w}_n \\ \hline & & & \end{array} \right].$$

17. Prove, with the setup as in the problem above, that the linear transformation T really is **unique**.

18. Consider two matrices A and B whose product AB is defined. Describe the i th row of the product AB in terms of the rows of A and the matrix B .