## Fundamental theorems of calculus

Note: In each of the following theorems, hypotheses on continuity of the integrand and "niceness" of the relevant region are omitted in order to focus on other details.

## Fundamental Theorem for Definite Integrals

If $F^{\prime}(x)=f(x)$, then $\int_{a}^{b} f(x) d x=F(b)-F(a)$.
By substituting, we can also write the conclusion as

$$
\int_{a}^{b} F^{\prime}(x) d x=F(b)-F(a)
$$

## Fundamental Theorem for Line Integrals

Let $C$ be a curve that starts at $A$ and ends at $B$. If $\vec{\nabla} V=\vec{F}$, then

$$
\int_{C} \vec{F} \cdot d \vec{r}=V(B)-V(A) .
$$

By substituting, we can also write the conclusion as

$$
\int_{C} \vec{\nabla} V \cdot d \vec{r}=V(B)-V(A)
$$

## Divergence Theorem

Let $D$ be a solid region with the closed surface $S$ as the edge of $D$ and area element vectors $d \vec{A}$ for $S$ oriented outward. If $\vec{\nabla} \cdot \vec{F}=f$, then

$$
\iiint_{D} f d V=\oiint \oiint_{S} \vec{F} \cdot d \vec{A} .
$$

By substituting, we can also write the conclusion as

$$
\iiint_{D}(\vec{\nabla} \cdot \vec{F}) d V=\oiint_{S} \vec{F} \cdot d \vec{A} .
$$

## Stokes' Theorem

Let $S$ be a surface with the closed curve $C$ as the edge of $S$. Orient the area element vectors $d \vec{A}$ and the curve $C$ to have a right-hand relation. If $\vec{\nabla} \times \vec{F}=\vec{G}$, then

$$
\iint_{S} \vec{G} \cdot d \vec{A}=\oint_{C} \vec{F} \cdot d \vec{r}
$$

By substituting, we can also write the conclusion as

$$
\iint_{S}(\vec{\nabla} \times \vec{F}) \cdot d \vec{A}=\oint_{C} \vec{F} \cdot d \vec{r} .
$$

## Green's Theorem

We can derive Green's Theorem as a special case of Stokes' Theorem. Consider a vector field of the form $\vec{F}=P(x, y) \hat{\imath}+Q(x, y) \hat{\jmath}+0 \hat{k}$. Note that the curl of $\vec{F}$ is

$$
\vec{\nabla} \times \vec{F}=(0-0) \hat{\imath}-(0-0) \hat{\jmath}+\left(\frac{\partial Q}{\partial x}-\frac{\partial P}{\partial y}\right) \hat{k}=\left(\frac{\partial Q}{\partial x}-\frac{\partial P}{\partial y}\right) \hat{k} .
$$

Let $D$ be a planar region in the $x y$-plane with the closed curve $C$ as the edge of $D$. Orient the curve $C$ counterclockwise. If we think of $D$ as a surface, we can express the area element vectors as $d \vec{A}=d x d y \hat{k}$.
We now compute

$$
(\vec{\nabla} \times \vec{F}) \cdot d \vec{A}=\left(\frac{\partial Q}{\partial x}-\frac{\partial P}{\partial y}\right) \hat{k} \cdot d x d y \hat{k}=\left(\frac{\partial Q}{\partial x}-\frac{\partial P}{\partial y}\right) d x d y
$$

Using this special case in the conclusion of Stokes' Theorem, we get

$$
\iint_{D}\left(\frac{\partial Q}{\partial x}-\frac{\partial P}{\partial y}\right) d x d y=\oint_{C}(P \hat{\imath}+Q \hat{\jmath}) \cdot d \vec{r}
$$

Using an alternate notation for line integrals, this can also be written as

$$
\iint_{D}\left(\frac{\partial Q}{\partial x}-\frac{\partial P}{\partial y}\right) d x d y=\oint_{C} P d x+Q d y
$$

## Common structure among these fundamental theorems

The theorems given above all have the same all of which have the same basic structure: Integrating the derivative of a function over a region gives the same value as integrating the function itself over the edge of the region. In the case of a one-dimensional region such as a curve, the edge consists of only two points so integrating over the edge reduces to simply adding together two values. Here's how this basic idea plays out in the specific cases:

- In the Fundamental Theorem for Definite Integrals, the region is an interval $[a, b]$ on the input axis so the edge of the region consists of two points $a$ and $b$ on the axis. The function is a function of one variable and the derivative is the first kind of derivative you learned about. In words, the theorem says that integrating the derivative $F^{\prime}$ over the interval $[a, b]$ is the same as adding up the function $F$ for the two endpoints. But wait, isn't $F(b)-F(a)$ a difference rather than a sum? Yes, but we can think of it as $(-1) F(a)+F(b)$. The factor of -1 relates to the issue of orientation. At $a$, the direction pointing out is the negative direction while at $b$, the outward pointing direction is the positive direction. The factor of -1 reflects the fact that the outward direction at $a$ is the negative direction.
- In the Fundamental Theorem for Line Integrals, the region is a curve $C$ so the edge consists of two points $A$ and $B$ or on the plane or in space. The function is a function of two or more variable and the derivative is the gradient. In
words, the theorem says that integrating the gradient $\vec{\nabla} V$ over the curve $C$ is the same as adding up the function $V$ for the two endpoints. We usually write this as $V(B)-V(A)$ but can think of it as $(-1) V(a)+V(b)$. As above, the factor of -1 relates to the issue of orientation and is related to the fact that $d \vec{r}$ points into the curve at $A$ and out of the curve at $B$.
- In Green's Theorem, the region is a planar region $D$ with edge consisting of a closed curve $C$. The function is a planar vector field and the derivative is the $\hat{k}$ component of the curl (which is the only non-zero component of the curl for a planar vector field). In words, the theorem says that integrating the curl $\partial Q / \partial x-\partial P / \partial y$ over the region $D$ is the same as integrating the vector field $P \hat{\imath}+Q \hat{\jmath}$ over the curve $C$.
- In Stoke's Theorem, the region is a surface $S$ in space with edge consisting of a closed curve $C$. The function is a vector field and the derivative is the curl. In words, the theorem says that integrating the curl $\vec{\nabla} \times \vec{F}$ over the surface $S$ is the same as integrating the vector field $\vec{F}$ over the curve $C$.
- In the Divergence Theorem, the region is a solid region in space with edge consisting of a closed surface $S$. The function is a vector field and the derivative is the divergence. In words, the theorem says that integrating the divergence $\vec{\nabla} \cdot \vec{F}$ over the solid region $D$ is the same as integrating the vector field $\vec{F}$ over the surface $S$.

We can also organize these in terms of the dimension of the region and its edge:

- In the Fundmental Theorems for Definite Integrals and Line Integrals, the region is one-dimensional (an interval or a curve) and the edge is zero-dimensional (a set of two points).
- In Green's Theorem and Stoke's Theorem, the region is two-dimensional (a planar region or a surface) and the edge is one-dimensional (a curve).
- In the Divergence Theorem, the region is three-dimensional (a solid region) and the edge is two-dimensional (a surface).


## Importance of the fundamental theorems

The fundamental theorems are important for both aesthetic value and as useful tools. Aesthetically, the fundamental theorems provide a beautiful unity among the various types of function, derivative, and integral we have explored in calculus. As tools, we use the fundamental theorems in two primary ways:

- Rather than evaluate an integral directly, we can trade it in for a related expression that is easier to evaluate. You are very familiar with doing this when you trade in a definite integral $\int_{a}^{b} f(x) d x$ for the sum $(-1) F(a)+F(b)=$ $F(b)-F(a)$. Problems 1,3, and 4 give you practice with this type of "trading in" using the other fundamental theorems.
- Given information about the derivative of a function at each point in a region, we can deduce information about certain integrals for the function itself (and vice versa). Problem 2 gives you an example of this use.


## Problems: Fundamental theorems of calculus

1. Use the Divergence Theorem to evaluate $\oiint_{S} \vec{F} \cdot d \vec{A}$ where

$$
\vec{F}=(z-x) \hat{\imath}+(x-y) \hat{\jmath}+(y-z) \hat{k}
$$

and $S$ is the sphere of radius 4 centered at the origin with $d \vec{A}$ oriented outward.

$$
\text { Answer: } \oiint \int_{S} \vec{F} \cdot d \vec{A}=-256 \pi
$$

2. Suppose that $\vec{F}$ is a vector field with $\vec{\nabla} \cdot \vec{F}=0$ for all points in $\mathbb{R}^{3}$. Show that $\oiint_{S} \vec{F} \cdot d \vec{A}=0$ for any closed surface $S$ in $\mathbb{R}^{3}$.
3. Use Stokes' Theorem (or Green's Theorem) to evaluate $\oint_{C} \vec{F} \cdot d \vec{r}$ where $\vec{F}=y^{2} \hat{\imath}-x^{2} \hat{\jmath}$ and $C$ is the square in the $x y$-plane with corners at $(0,0),(1,0)$, $(1,1)$, and $(0,1)$ traversed counterclockwise.

$$
\text { Answer: } \oint_{C} \vec{F} \cdot d \vec{r}=-2
$$

4. Suppose $C$ is a simple closed curve in the $x y$-plane. Let $\vec{F}=-y \hat{\imath}+x \hat{\jmath}$ and consider the line integral $\oint_{C} \vec{F} \cdot d \vec{r}$. Use Stokes' Theorem (or Green's Theorem) to relate the value of this line integral to the area of the region enclosed by $C$. Note: A simple curve is one with no self-intersections so a simple closed curve is a loop with no self-interesections.
5. Use your result from Problem 4 to compute the area enclosed by the ellipse $\frac{x^{2}}{a^{2}}+\frac{y^{2}}{b^{2}}=1$.
