

November 14, 2006

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Name

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**Directions:** Only write on one side of each page.

**Do any six (6) of the following**

1. Let  $K \subset H \subset G$  be subgroups of a **finite** group  $G$ . Prove the formula

$$[G : K] = [G : H][H : K].$$

- (a) The basic formula is that  $|G| = [G : H]|H|$  for every group  $G$  and every subgroup  $H$  of  $G$ . Thus

$$[G : K] = \frac{|G|}{|K|} = \frac{|G|}{|H|} \frac{|H|}{|K|} = [G : H][H : K].$$

2. Do **both** of the following:

- (a) If  $S$  is a set and  $G$  is a group acting on  $S$ , prove that the relation

$$s \sim s' \text{ if } s' = gs \text{ for some } g \in G$$

is an equivalence relation.

- i. Reflexive:  $es = s$ , symmetric:  $gs_1 = s_2$  implies  $s_1 = g^{-1}s_2$ , transitive:  $gs_1 = s_2$  and  $hs_2 = s_3$  implies  $(hg)s_1 = h(gs_1) = s_3$
- (b) Let  $\phi : G \rightarrow G'$  be a homomorphism, and let  $S$  be a set on which  $G'$  acts. Use  $\phi$  to define, with proof, a group action of  $G$  on  $S$ .
- i. Given the group action  $g's$  for the group  $G'$  define a group action for the group  $G$  by  $gs = \phi(g)s = g's$  where  $\phi(g) = g'$ . Then  $es = \phi(e)s = e's = s$  and  $g_2(g_1s) = g_2(g'_1s) = \phi(g_2)(g'_1s) = g'_2(g'_1s) = (\phi(g_1)\phi(g_2))s = \phi(g_2g_1)s = (g_2g_1)'s = (g_2g_1)s$ .

3. Do one of the following

- (a) Let  $G$  be a group containing normal subgroups of orders 3 and 5, respectively. Prove  $G$  contains an element of order 15.
- i. Let  $H$  have order 3 and  $K$  have order 5. Normality of  $H$  and  $K$  in  $G$  tells us that  $hkh^{-1}k^{-1} = (hkh^{-1})k^{-1} = h(kh^{-1}k^{-1})$  is an element in  $H \cap K$ . But  $H \cap K \leq H$  and  $H \cap K \leq K$  so  $|H \cap K|$  divides both 3 and 5 and so there is only one element,  $e$ , in  $H \cap K$ . Thus,  $hkh^{-1}k^{-1} = e$  so  $hk = kh$  for every  $h \in H$  and  $k \in K$ . Now let  $a$  be the generator of the cyclic group  $H$  and  $k$  the generator of the cyclic group  $K$ . The element  $ab$  of  $G$  satisfies  $(ab)^n = a^n b^n$  and the smallest positive number  $n$  for which this yields  $e$  must have both 3 and 5 as divisors. Thus  $n = 15$  is the order of the element  $ab$  in  $G$ .
- (b) Let  $H, K$  be subgroups of a group  $G$ . Show the set of products  $HK = \{hk : h \in H, k \in K\}$  is a subgroup if and only if  $HK = KH$ .

- i. “ $\rightarrow$ ” If  $HK \leq G$ 
  - A.  $kh = (h^{-1}k^{-1})^{-1} \in HK$  by closure of subgroups and  $KH \subset HK$ .
  - B.  $KH$  is closed under inverses since  $(kh)^{-1} = h'k' \in HK$  so  $hk = (k^{-1}h^{-1})^{-1} \in KH$  and  $KH = HK$
- ii. “ $\leftarrow$ ” If  $HK = KH$  then  $(h_1k_1)(h_2k_2)^{-1} = h_1(k_1h_2^{-1})k_2^{-1} = h_1(h_3k_3)k_2 \in HK$  so  $HK$  is a subgroup by the 1 step theorem.

4. Do one of the following:

When we classified the group  $M$  of rigid motions of the plane we claimed the following six relations were all true and proved a few of them.

(a) Add to our certainty by **algebraically** proving either part iv. or part v.

i.  $t_a t_b = t_{a+b}$

ii.  $\rho_\theta \rho_\eta = \rho_{\theta+\eta}$

iii.  $rr = i$

iv.  $\rho_\theta t_a = t_{a'} \rho_\theta$ , where  $a' = \rho_\theta(a)$

v.  $rt_a = t_{a'} r$ , where  $a' = r(a)$

A. Write out  $rt_a(x)$  and  $t_{a'}r(x)$  using the functions below to see that they are equal for all  $x$ .

vi.  $r\rho_\theta = \rho_{-\theta}r$ .

(b) Use the above relations to show that if  $m$  is an orientation reversing motion of the plane then  $m^2$  is a translation.

i.

$$\begin{aligned} m^2 &= (t_a \rho r)(t_a \rho r) = t_a \rho t_{a'} r \rho r = \\ &= t_a \rho t_{a'} \rho^{-1} r r = t_a \rho t_{a'} \rho^{-1} \\ &= t_a t_{a''} \rho \rho^{-1} \\ &= t_{a+a''} \end{aligned}$$

(c) Compute the glide vector of the glide  $t_{\vec{a}} \rho_\theta r$  in terms of  $\vec{a}$  and  $\theta$ .

5. Do one of the following:

(a) Let  $G$  be a group and  $Aut(G)$  the group of automorphisms of  $G$ . Prove or disprove: The set of inner automorphisms  $Inn(G) = \{\phi \in Aut(G) : \phi(g) = xgx^{-1} \text{ for some } x \in G\}$  is a normal subgroup of  $Aut(G)$ .

i.  $\phi, \psi \in Inn(G)$  where  $\phi(g) = xgx^{-1}$  and  $\psi(g) = ygy^{-1}$ , then  $\phi \circ \psi^{-1}(g) = \phi(y^{-1}gy) = xy^{-1}gyx^{-1} = (xy^{-1})g(xy^{-1})^{-1} \in Inn(G)$  so  $Inn(G)$  is a subgroup by the one step test.

ii. Let  $f$  be an automorphism and  $\phi \in Inn(G)$  as above then  $f\phi f^{-1}(g) = f(xf^{-1}(g)x^{-1}) = f(x)f(f^{-1}(g))f(x^{-1}) = (f(x))g(f(x))^{-1} \in Inn(G)$

(b) Let  $S$  be a set on which a group  $G$  operates. Let  $H = \{g \in G : gs = s \text{ for all } s \in S\}$ . Prove  $H$  is a normal subgroup of  $G$ .

i. Let  $x \in G$  and  $h \in H$  then  $(xhx^{-1})s = x(h(x^{-1}s)) = x(x^{-1}(s)) = es = s$  so  $H$  is normal in  $G$ .

6. The following patterns represent small portions of two tilings of the infinite plane. Circle one of the following patterns and let  $G$  be the group of symmetries of that tiling. Determine the point group of  $G$ .

- (a) See attached image file for the patterns
- (b) #1: If the pattern repeats to cover the plane then the smallest angle of rotation is  $\pi$  and there are horizontal reflections so the point group is  $D_2$ . If the pattern is restricted to an infinite horizontal strip then the smallest angle of rotation is  $2\pi$  and the point group is  $D_1$ .
- (c) #2: Similarly, for a plane-filling pattern the point group is  $D_2$  and for an infinite strip it is again  $D_2$ .
7. Let  $G$  be a group acting on the set  $S$ . Let  $s$  be a fixed element in  $S$  and  $t$  an element in the orbit of  $s$ , say  $t = as$ . Prove the stabilizer of  $t$  in  $G$  is a conjugate subgroup of the stabilizer of  $s$  in  $G$ . Specifically, show  $G_t = aG_s a^{-1}$ .
- (a)  $g \in G_t$  iff  $gt = t$  iff  $g(as) = as$  iff  $(a^{-1}ga)s = s$  iff  $a^{-1}ga \in G_s$  iff  $g = a(a^{-1}ga)a^{-1} \in aG_s a^{-1}$ .
8. Determine the group of automorphisms  $Aut(G)$  if  $G = C_2 \times C_2$ .

### Useful Facts

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$$\rho_\theta \left( \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \right) = \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$r \left( \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \right) = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$