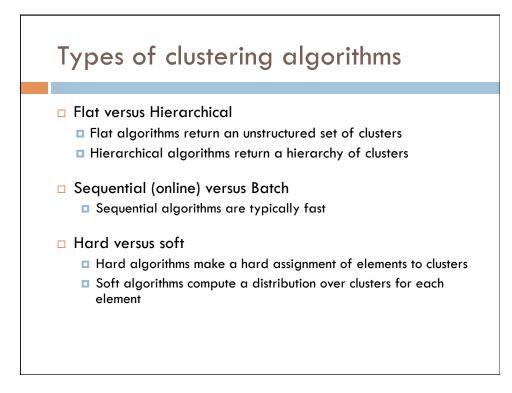


Terminology

- □ An m-clustering of D is a partition of D into sets (clusters) $C_1, C_2, ..., C_m$ such that
 - The clusters are non-empty
 - The union of the clusters is D
 - The intersection of the clusters is empty
- The centroid of a cluster is the mean of all the elements in the cluster



K-means Clustering is an old algorithm

"If someone is found slain, lying in a field in the land the Lord your God is giving you to possess, and it is not known who the killer was, your elders and judges shall go out and measure the distance from the body to the neighboring towns. Then the elders of the town nearest the body shall..."

- Deuteronomy 21

K-means Clustering

- The most well-known (widely-used) clustering algorithm
- Minimizes the sum of the squared distances of each vector from its centroid:

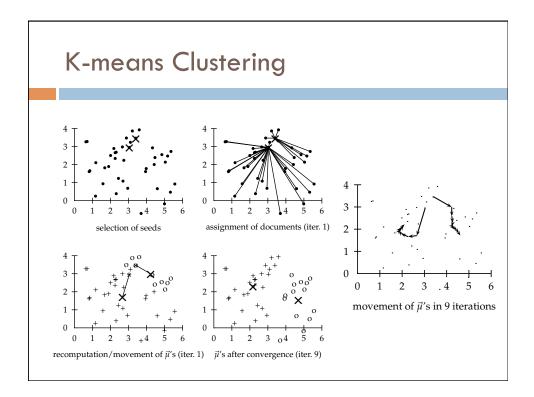
$$RSS = \sum_{k=1}^{K} \sum_{\vec{x} \in C_k} ||\vec{x} - \mu_k||_2^2$$

Residual sum of squares

- User must set K
- Assumes instances x represented as normalized vectors in a real-valued space

K-means Clustering

K-MEANS $(\{\vec{x}_1,\ldots,\vec{x}_N\},K)$ $(\vec{s}_1, \vec{s}_2, \dots, \vec{s}_K) \leftarrow \text{SELECTRANDOMSEEDS}(\{\vec{x}_1, \dots, \vec{x}_N\}, K)$ 1 for $k \leftarrow 1$ to K2 3 **do** $\vec{\mu}_k \leftarrow \vec{s}_k$ 4 while stopping criterion has not been met 5 **do for** $k \leftarrow 1$ **to** K6 **do** $\omega_k \leftarrow \{\}$ for $n \leftarrow 1$ to N 7 8 **do** $j \leftarrow \arg \min_{j'} |\vec{\mu}_{j'} - \vec{x}_n|$ $\omega_i \leftarrow \omega_i \cup \{\vec{x}_n\}$ (reassignment of vectors) 9 for $k \leftarrow 1$ to K10 **do** $\vec{\mu}_k \leftarrow \frac{1}{|\omega_k|} \sum_{\vec{x} \in \omega_k} \vec{x}$ (recomputation of centroids) 11 12 return $\{\vec{\mu}_1,\ldots,\vec{\mu}_K\}$



K-means Clustering

Starting seeds (centroids)

- Randomly select K initial data points to be the centroids
- Run multiple K-means each with different random seeds
- Use results from a different clustering algorithm (run on random subset of data)
- Stopping criteria
 - See IR for a number of possible stopping criteria. For example:
 - Fixed number of iterations
 - Residual sum of squares (RSS) falls below threshold

□ Choosing K

- Rules-of-thumb or experience
- Try multiple values for K and plot RSS. Look for the elbow.
- Add regularization term

Flat versus Hierarchical

- K-means
 - Returns unstructured set of clusters
 - Requires user to determine K
 - Non-deterministic
 - Linear run time O(IKNM)
- Hierarchical (e.g. Agglomerative clustering)
 - Returns a hierarchy of clusters
 - No need to (initially) determine K
 - Deterministic
 - Quadratic run time

Hierarchical Clustering

- Cluster data points based on distance metric or similarity measure
- A metric is a function that assigns a positive real-valued number (representing distance) to every pair of vectors in some vector space
- □ Minkowski distance is given by

$$d_p(\vec{x}_i, \vec{x}_j) = \left(\sum_{m=1}^M |x_{im} - x_{jm}|^p\right)^{1/p}$$

Hierarchical Clustering

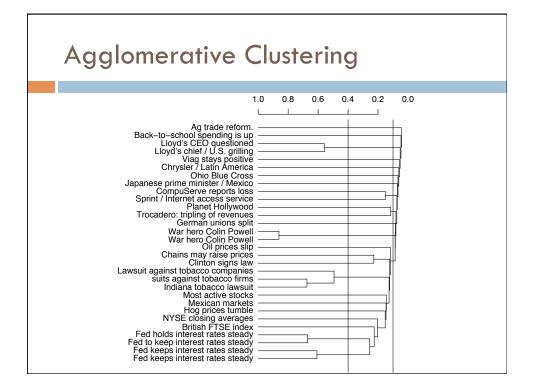
 For p = 1, Manhattan distance d₁(\$\vec{x}_i\$, \$\vec{x}_j\$) = \$\sum_{m=1}^{M} |x_{im} - x_{jm}|\$
For p = 2, Euclidean distance d₂(\$\vec{x}_i\$, \$\vec{x}_j\$) = \$\left(\sum_{m=1}^{M} |x_{im} - x_{jm}|^2\right)^{1/2}\$

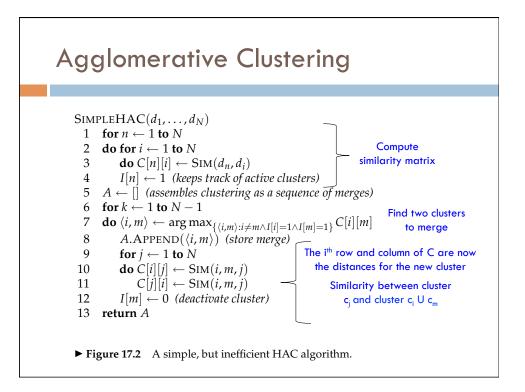
Cosine similarity also common measure (Note inverse of distance)

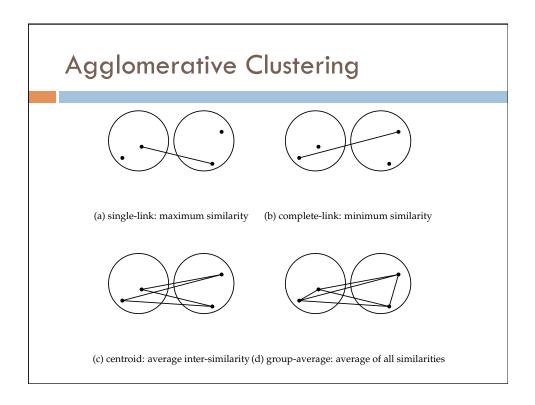
$$\cos(\vec{x}_i, \vec{x}_j) = \frac{\vec{x}_i^{\mathsf{T}} \vec{x}_j}{||\vec{x}_i||_2 ||\vec{x}_j||_2} = \frac{\sum_{m=1}^M x_{im} \cdot x_{jm}}{||\vec{x}_i||_2 ||\vec{x}_j||_2}$$

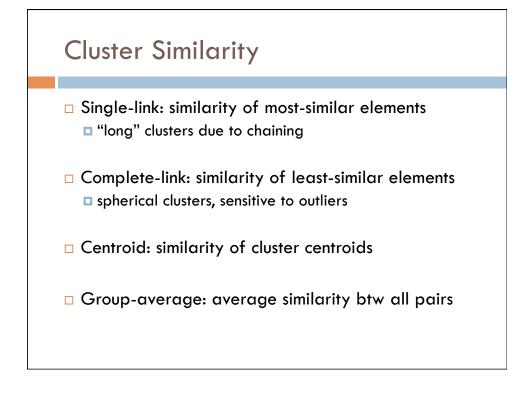


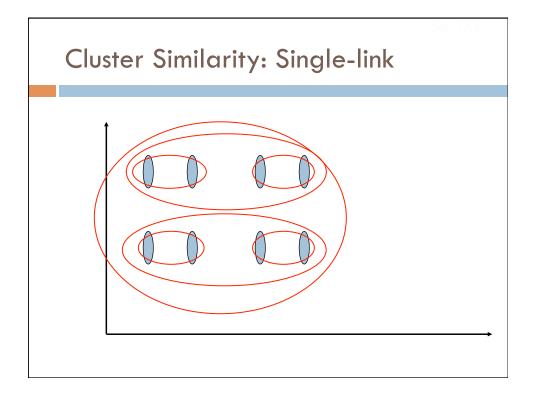
- Agglomerative clustering
 - Start with N clusters each with one data point
 - Merge similar clusters to form larger clusters until there is only a single cluster left
- Divisive Clustering
 - Start with a single cluster containing all data points
 - Divide large clusters into smaller clusters until each cluster contains a single data point

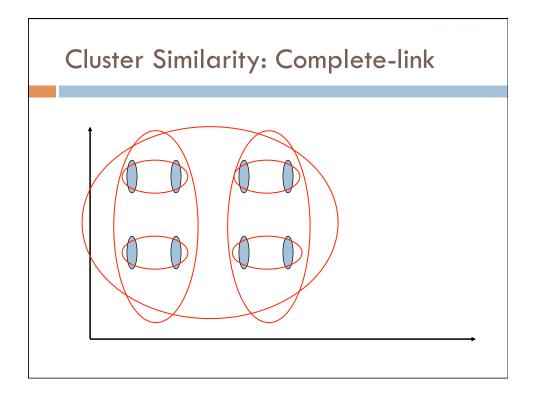


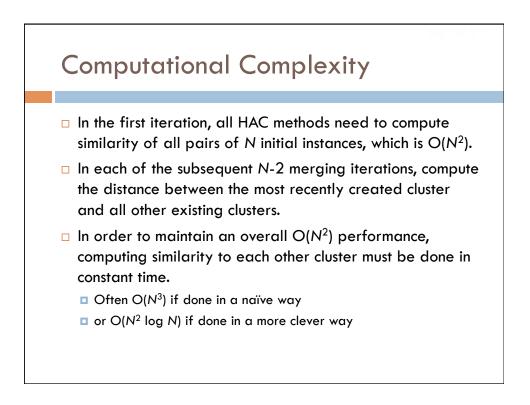






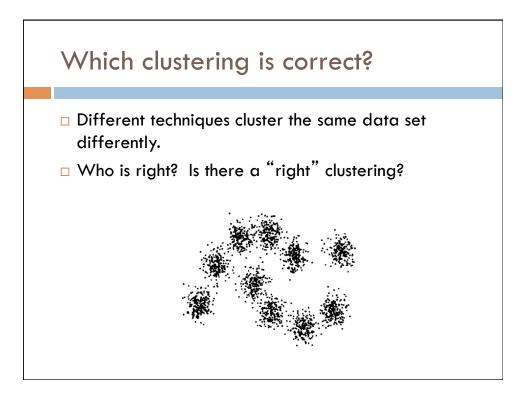


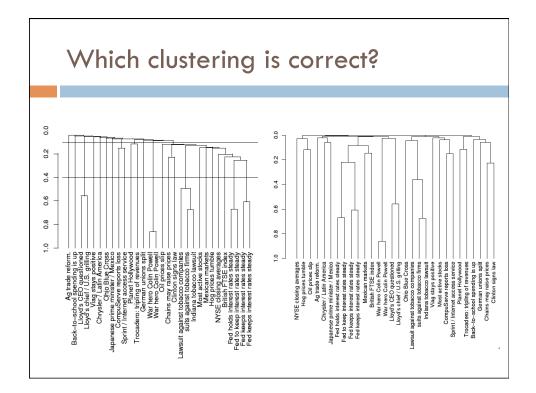


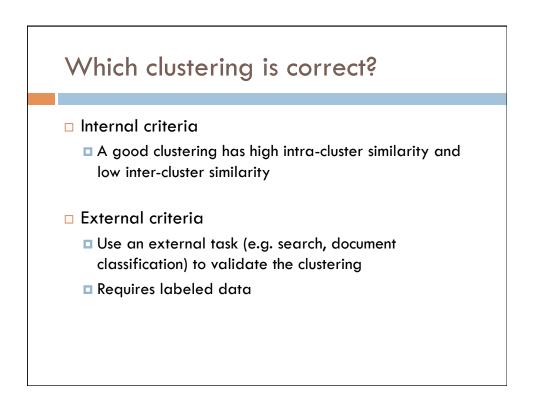


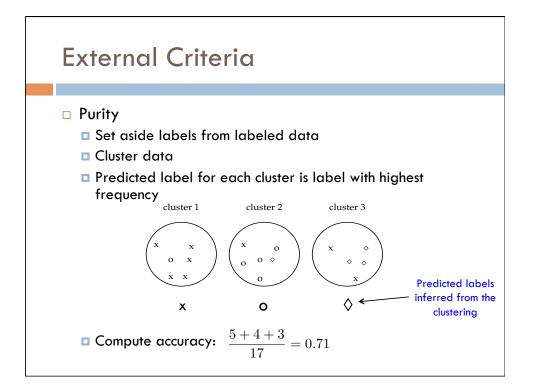
Divisive Clustering

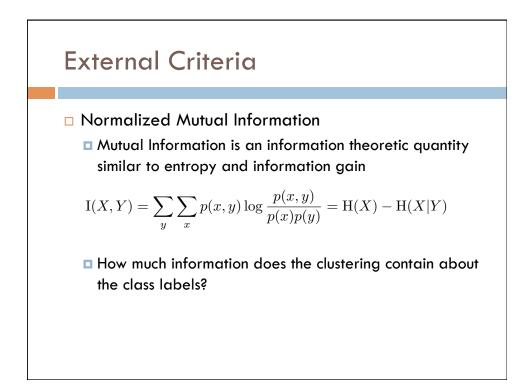
- □ Top-down clustering
- Divisive clustering algorithm uses a flat clustering algorithm as a subroutine
 - Start with all data points in one cluster
 - Split using a flat clustering algorithm
 - Apply recursively until each data point is in its own cluster
- Can be more efficient than agglomerative
- Benefits from complete information about the entire data set

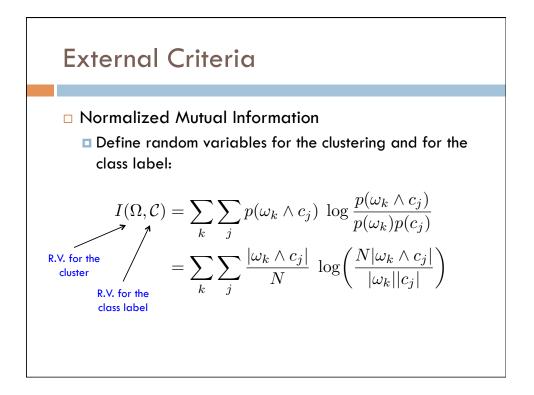


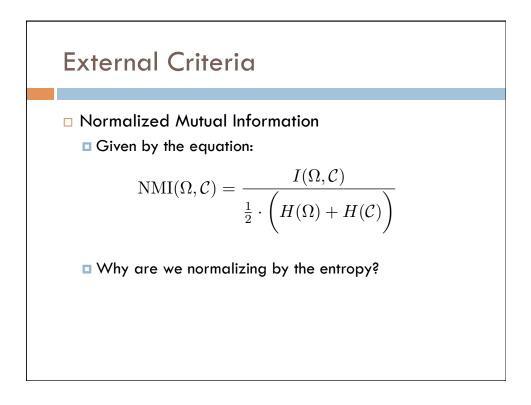


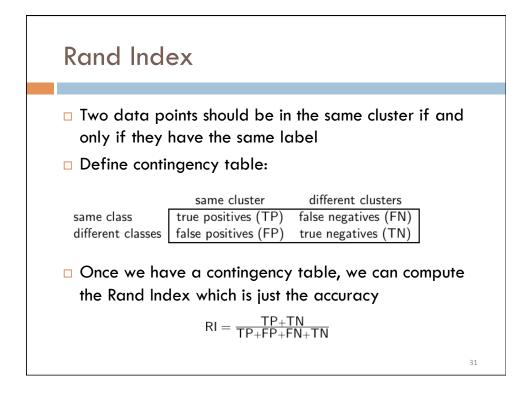


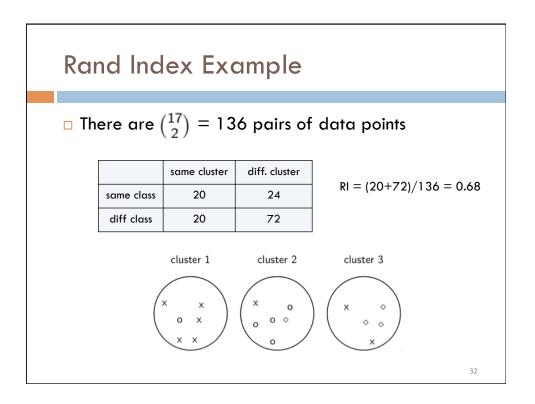












F-measure

 Given the contingency table, we can compute the precision, recall, and F-measure

$$P = \frac{TP}{TP + FP} \qquad R = \frac{TP}{TP + FN}$$
$$\cdot$$
$$F_{\beta} = (1 + \beta^2) \cdot \frac{\text{precision} \cdot \text{recall}}{\beta^2 \cdot \text{precision} + \text{recall}}$$

 \square The parameter β controls the weighting between precision and recall

Clustering Evaluation					
	purity	NMI	RI	F_5	
lower bound	0.0	0.0	0.0	0.0	
maximum	1.0	1.0	1.0	1.0	
value for example	0.71	0.36	0.68	0.46	
All four measures range from 0 (really bad clustering) to 1 (perfect clustering).					
					34