## NEURAL NETWORKS

## Recap: Decision Trees



## Learning a Decision Tree

function DECISION-TREE-LEARNING (examples, attributes, parents) returns a tree
if examples is empty return MAJORITY_VOTE(parents)
else if all examples have same classification return classification
else if attributes is empty return MAJORITY_VOTE(examples)
else
$\mathrm{A} \longleftarrow$ CHOOSE-BEST-ATTRIBUTE (examples)
tree $\longleftarrow$ a new decision tree with root $A$
for each value $v_{k}$ of $A$
$\mathrm{S}_{\mathrm{k}} \quad \longleftarrow$ examples with value $\mathrm{v}_{\mathrm{k}}$ for attribute A
subtree $\longleftarrow$ DECISION-TREE-LEARNING( $\mathrm{S}_{\mathrm{k}}$, attributes-A, examples) add branch to tree with label $\left(A=v_{k}\right)$ and subtree
return tree

## Choosing the best attribute

## Splitting on a good attribute

$\square$ After the split, the examples at each branch have the same classification

## Splitting on a bad attribute

$\square$ After the split, the examples at each branch have the same proportion of positive and negative examples

We will use entropy and information gain to formalize what we mean by good and bad attributes

## Entropy

Entropy measures the uncertainty of a random variable

- How many bits are needed to efficiently encode the possible values (outcomes) of a random variable?
$\square$ Introduced by Shannon in 1948 paper
$\square$ Example: flipping a coin
$\square$ A completely biased coin requires 0 bits of entropy
- A fair coin requires 1 bit of entropy

- How many bits are need to encode the outcome of flipping a fair coin twice?


## Entropy and Information Gain

Let $A$ be a random variable with values $v_{k}$
Each value $\mathrm{v}_{\mathrm{k}}$ occurs with probability $\mathrm{p}\left(\mathrm{v}_{\mathrm{k}}\right)$
Then the entropy of $A$ is defined as

$$
\begin{aligned}
H(A) & =\sum_{k} p\left(v_{k}\right) \log _{2}\left(\frac{1}{p\left(v_{k}\right)}\right) \\
& =-\sum_{k} p\left(v_{k}\right) \log _{2} p\left(v_{k}\right)
\end{aligned}
$$

(Apply this notion of entropy to choosing the best attribute)


## Decision Trees: additional considerations

$\square$ Overfitting can be caused by many factors
$\square$ Noisy data, irrelevant attributes, spurious correlations, nondeterminism

Can cause additional nodes to be added to the


## Decision Trees: additional considerations



## Decision Trees: additional considerations

Overfitting$\square$ Can post-process the learned decision tree and prune using significance testing at final nodes
$\square$ Cross-validation using validity set
$\square$ Continuous or integer-valued attributes
$\square$ Use ranges
$\square$ Continuous label y
Combination of splitting and linear regression

## Today

Reading

- AIMA 18.6-18.8
$\square$ Note: 18.6 covers regression but also sets up the mathematical background/notation for neural networks

Goals
$\square$ Perceptron (networks)
$\square$ Perceptron training rule

- Feed-forward neural networks
$\square$ (Backpropagation)


## Our Nervous System



## A single perceptron



## Activation function


$\square$ The activation function determines if the "electrical signal" entering the neuron is sufficient to cause it to fire
$\square$ Threshold function - range is $\{0,1\}$
$\square$ Sigmoid function - range $[0,1]$
$\square$ Hyperbolic tangent function - range [-1,1]


## Example: logical operators

AND: If all inputs are 1, return 1. Otherwise return 0 OR: If at least one input is 1 , return 1 . Otherwise return 0
NOT: Return the opposite of the input
XOR: If exactly one input is 1 , then return 1 .
Otherwise return 0

| $x_{1}$ | $x_{2}$ | $x_{1}$ and $x_{2}$ |
| :---: | :---: | :---: |
| 0 | 0 | 0 |
| 0 | 1 | 0 |
| 1 | 0 | 0 |
| 1 | 1 | 1 |





OR

| $x_{1}$ | $x_{2}$ | $x_{1}$ or $x_{2}$ |
| :---: | :---: | :---: |
| 0 | 0 | 0 |
| 0 | 1 | 1 |
| 1 | 0 | 1 |
| 1 | 1 | 1 |



OR


## NOT

| $x_{1}$ | $\operatorname{not} x_{1}$ |
| :---: | :---: |
| 0 | 1 |
| 1 | 0 |

NOT

Input $x_{1} \xrightarrow{W_{1}=?} T=$ ? $\longrightarrow$ Output $y$

## NOT

 If input is 0 , output is 1



Linearly Separable



## Linearly Separable

$$
\begin{array}{c|c|cc}
x_{1} & x_{2} & x_{1} \text { and } x_{2} \\
\hline 0 & 0 & 0 & \\
0 & 1 & 0 & \\
1 & 0 & 0 & \\
1 & 1 & 1 &
\end{array}
$$



## Linearly Separable

$$
\begin{array}{c|c|cc|c|cc}
x_{1} & x_{2} & x_{1} \text { and } x_{2} & & x_{1} & x_{2} & x_{1} \text { or } x_{2} \\
\hline 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 1 & 1 & 0 \\
1 & 0 & 0 & 1 & 0 & 1 & 0 \\
1 & 1 & 1 & 1 & 1 & 1 &
\end{array}
$$



Perceptrons: Linearly separable functions

| $\mathrm{x}_{1}$ | $\mathrm{x}_{2}$ | $\mathrm{x}_{1}$ and $\mathrm{x}_{2}$ | $\mathrm{x}_{1}$ | $\mathrm{x}_{2}$ | $\mathrm{x}_{1}$ or $\mathrm{x}_{2}$ | $\mathrm{x}_{1}$ | $\mathrm{x}_{2}$ | $\mathrm{x}_{1}$ xor $\mathrm{x}_{2}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| 0 | 1 | 0 | 0 | 1 | 1 | 0 | 1 | 1 | 0 |
| 1 | 0 | 0 | 1 | 0 | 1 | 1 | 0 | 1 | 0 |
| 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 |



## Perceptron Training rule

Need an algorithm for finding a set of weights w such that

- The predicted output of the neural network matches the true output for all examples in the training set
$\square$ Predicts a reasonable output for inputs not in the training set


## Perceptron Training Rule

1. Begin with randomly initialized weights
2. Apply the perceptron to each training example (each pass through examples is called an epoch)
3. If it misclassifies an example modify the weights
4. Continue until the perceptron classifies all training examples correctly

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(Derive gradient-descent update rule)
