## ENSEMBLE METHODS

## Today

$\square$ Reading
$\square$ AIMA 18.10-18.11
$\square$ Goals
$\square$ (Recap support vector machines)
$\square$ Ensembles of classifiers

## What defines a hyperplane?

A hyperplane is defined by:A vector w$\square$ Perpendicular to the hyperplane

- Often called the "weight" vector
$\square$ A scalar b
$\square$ Selects the hyperplane that is distance $b$ from the origin from among all possible hyperplanes



## Deriving a support vector machine

|  | - $x^{i}$ is the $i^{\text {th }}$ training example $r_{0}$ is any point on the decision boundary $w$ is the weight vector which is perpendicular to the decision boundary The geometric margin of $\mathrm{x}_{\mathrm{i}}$ is given by $\gamma^{i}$ The geometric margin is equal to the length of the projection of ( $x^{i}-r_{0}$ ) onto the vector w The length of the projection of ( $x^{i}-r_{0}$ ) onto the vector $w$ is given by: $\begin{aligned} \gamma^{(i)} & =\frac{\left(x^{(i)}-r_{0}\right) \cdot w}{\\|w\\|} \\ & =\frac{w \cdot x^{(i)}-r_{0} \cdot w}{\\|w\\|} \\ & =\frac{w \cdot x^{(i)}+b}{\\|w\\|} \end{aligned}$ <br> where $b=-r_{0} \cdot w$ |
| :---: | :---: |



## Recap: Solving the Optimization Problem

$\min _{w, b} \frac{1}{2}\|w\|^{2}$ such that $y^{(i)}\left(w^{\top} x^{(i)}+b\right) \geq 1 \quad \forall i$

- Need to optimize a quadratic function subject to linear constraints
- Quadratic optimization problems are a well-known class of mathematical programming problem and many algorithms exist for solving them
- The solution involves constructing a dual problem where a Lagrange multiplier (a scalar value) is associated with every constraint in the primary problem


## Solving the Optimization Problem

$\min _{w, b} \frac{1}{2}\|w\|^{2}$ such that $y^{(i)}\left(w^{\top} x^{(i)}+b\right) \geq 1 \quad \forall i$
$\left.\max _{\substack{\text { Lagrange } \\ \text { multipliers }}}^{\min _{w, b}} \frac{1}{2}\|w\|^{2}-\sum_{i=1}^{\downarrow_{N}} \alpha_{i}\left[y^{(i)}\left(w^{\top} x^{(i)}+b\right)-1\right] \quad{ }_{\downarrow}\right]$ Dual

$$
\max _{\alpha} \sum_{i=1}^{N} \alpha_{i}-\frac{1}{2} \sum_{i} \sum_{j} \alpha_{i} \alpha_{j} y^{(i)} y^{(j)} x^{(i)} x^{(j)}
$$

$$
\text { subject to } \alpha_{i} \geq 0 \text { and } \sum_{i} \alpha_{i} y^{(i)}=0
$$

## Solving the Optimization Problem

$\square$ The solution has the form:

$$
w=\sum_{i=1}^{N} \alpha_{i} y^{(i)} x^{(i)} \text { and } b=y^{(i)}-w^{\boldsymbol{\top}} x^{(i)} \text { for any } x^{(i)} \text { s.t. } \alpha_{i} \neq 0
$$

$\square$ Each non-zero alpha indicates corresponding $x_{i}$ is a support vector
$\square$ The classifying function has the form: $g\left(x_{i}\right)=\operatorname{sign}\left(\sum_{i} \alpha_{i} y^{(i)} x^{(i)} x+b\right)$

Relies on an inner product between the test point $x$ and the support vectors $\mathrm{X}_{\mathrm{i}}$

## Non-linear SVMs

$\square$ General idea: the original feature space can always be mapped to some higher-dimensional feature space where the training set is separable:


## The "Kernel" trick

The linear classifier relies on an inner product between vectors $x_{i}{ }^{\top} x_{i}$

$$
g\left(x_{i}\right)=\operatorname{sign}\left(\sum_{i} \alpha_{i} y^{(i)} x^{(i)} x+b\right)
$$

If every example is mapped into a high-dimensional space via some transformation $\Phi: \mathbf{x} \rightarrow \varphi(\mathbf{x})$ then the inner product becomes:

$$
g\left(x_{i}\right)=\operatorname{sign}\left(\sum_{i} \alpha_{i} y^{(i)} \varphi\left(x^{(i)}\right)^{\top} \varphi(x)+b\right)
$$

$\square$ A kernel function is some function that corresponds to a dot product in some transformed feature space:

$$
K\left(\mathbf{x}_{\mathrm{i}}, \mathbf{x}_{\mathrm{j}}\right)=\varphi\left(\mathbf{x}_{\mathbf{i}}\right)^{\top} \varphi\left(\mathbf{x}_{\mathrm{j}}\right)
$$

## The "Kernel" trick

The kernel K may be cheaper to compute then the transformation $\varphi$

- Implictly do the transformation

$$
\phi(x)=\left[\begin{array}{l}
x_{1} x_{1} \\
x_{1} x_{2} \\
x_{1} x_{3} \\
x_{2} x_{1} \\
x_{2} x_{2} \\
x_{2} x_{3} \\
x_{3} x_{1} \\
x_{3} x_{2} \\
x_{3} x_{3}
\end{array}\right] \quad K(x, z)=\left(\sum_{i=1}^{n} x_{i} z_{i}\right)\left(\sum_{j=1}^{n} x_{i} z_{i}\right)
$$

## Kernels

Why use kernels?
-Make non-separable problem separable.
-Map data into better representational space

Common kernels
-Linear

- Polynomial $K(x, z)=\left(1+\mathbf{x}^{\top} \mathbf{z}\right)^{\text {d }}$

■Radial basis function (infinite dimensional space)

$$
K\left(\mathbf{x}_{i}, \mathbf{x}_{j}\right)=e^{-\left\|\mathbf{x}_{i}-\mathbf{x}_{j}\right\|^{2} / 2 \sigma^{2}}
$$

## SVMs Summary

The classifier is a decision boundary (separating hyperplane)
Most "important" training points are support vectors which define the hyperplane
$\square$ Quadratic optimization algorithms can identify which training points are support vectors (vectors with non-zero Lagrange multipliers)
$\square$ In the dual formation and in classifying an example, the training points appear only inside inner products
Kernels allow us to efficiently map data to higher dimensional space


## Which classifier should I use?

## Is there a classifier that is optimal for all classification problems?

## Factors to take into account:

$\square$ How much training data is available?
$\square$ How simple/complex is the problem? (linear vs.
nonlinear decision boundary)

- How noisy/skewed is the training data?
$\square$ How stable is the problem over time?
$\square$ Is it a singly-labeled or multi-labeled problem? Are the labels correlated?


## How Much Data?

Learning theory (PAC learning)
$\square$ Gives theoretical bounds on how much training data you need for a given accuracy (AIMA 18.5)

Very Little

- There are empirical results that naïve Bayes should do well in such circumstances ( Ng and Jordan 2002 NIPS)
- The interesting theoretical answer is to explore semi-supervised training methods: Bootstrapping, EM over unlabeled documents, ...
- The practical answer is to get more labeled data as soon as you can
$\square$ A reasonable amount of data
- Start with SVMs
$\square$ A lot of data?
- expensive methods like SVMs (train time) or kNN (test time) are quite impractical
- Naïve Bayes! - with lots of data, simple methods work well


## Ensembles of Classifiers

Ensemble - A group of items viewed as a whole rather than individually
$\square$ An ensemble of classifiers - A group of classifiers whose predictions are combined to produce one final prediction

## Benefits

- Harder to make a wrong prediction
$\square$ More expressive hypothesis


## Ensemble of decision trees



Combine the prediction of each decision tree using majority vote
Variation of this called a Random Forest

## Ensemble of linear classifiers


$\square$ More expressive than any one linear classifier by itself

## Ensemble Schemes

$\square$ Multi-expert combination methods
$\square$ Global - All classifiers generate an output and all outputs are used in some way

- e.g. weighting, voting, averaging
- Local - A gating model chooses one (or very few) of the classifiers responsible for generating the output for a specific input
- e.g. mixture of experts
$\square$ Multi-stage combination
$\square$ Classifiers are trained with, or tested on, only the instances where the previous classifiers are not accurate enough
- e.g. cascading


## Boosting

## Boosting is one of the most common forms of

 constructing an ensemble of classifiers- Learn a series of weak classifiers, i.e. classifiers whose performance is slightly better than random chance
$\square$ Weight each weak classifier to create a final strong classifier
$\square$ Often the weight for each classifier is proportional to its accuracy
A well-known boosting algorithm is AdaBoost short for "Adaptive Boosting" (Freund and Schapire 1995)


## AdaBoost

```
function ADABOOST(examples, L,K) returns a weighted-majority hypothesis
    inputs: examples, set of N labeled examples ( }\mp@subsup{x}{1}{},\mp@subsup{y}{1}{}),\ldots,(\mp@subsup{x}{N}{},\mp@subsup{y}{N}{}
        L, a learning algorithm
        K}\mathrm{ , the number of hypotheses in the ensemble
    local variables: w, a vector of N example weights, initially 1/N
            h, a vector of }K\mathrm{ hypotheses
            z, a vector of K}\mathrm{ hypothesis weights
    for }k=1\mathrm{ to }K\mathrm{ do
        h}[k]\leftarrowL(examples,\mathbf{w}
        error }\leftarrow
        for j=1 to }N\mathrm{ do
        if }\mathbf{h}[k](\mp@subsup{x}{j}{})\not=\mp@subsup{y}{j}{}\mathrm{ then error }\leftarrow\mathrm{ error }+\mathbf{w}[j
            for }j=1\mathrm{ to }N\mathrm{ do
                if h}[k](\mp@subsup{x}{j}{})=\mp@subsup{y}{j}{}\mathrm{ then }\mathbf{w}[j]\leftarrow\mathbf{w}[j]\cdot error/(1- error )
            w}\leftarrow\operatorname{NORMALIZE(w)
            z}[k]\leftarrow\operatorname{log}(1-\mathrm{ error )}/\mathrm{ error
    return WEIGHTED-MAJORITY(h,z)
```


## AdaBoost

$\square$ Generates a sequence of weak classifiers each focusing on the errors of the previous classifier
$\square$ AdaBoost returns a strong classifier, i.e. a classifier that can perfectly classify the training data for large enough K

To classify a new example x:
$h(x)=\operatorname{sign}\left(\sum_{k=1}^{K} \mathbf{z}[k] h_{k}(x)\right) \quad$ where $\quad \mathbf{z}[k]=\log \left(\frac{1-\text { error }}{\text { error }}\right)$


## Bagging

## Short for "Bootstrap aggregating"

Given training set $D$$\square$ Generate $M$ new training sets $D_{i}$ where $\left|D_{i}\right|<|D|$ by sampling from $D$ with replacement
$\square$ This is a statistical technique known as bootstrapping
$\square$ Train a classifier on each of the $M$ new training sets
$\square$ Combine output of $M$ classifiers using averaging or voting

Random Forests (Breimen, 2001)
$\square$ Bagged decision trees

## Cascading classifiers

$\square$ Order classifiers by complexity, e.g.
representational complexity
$\square$ Use $i^{\text {th }}$ classifier $\mathrm{d}_{\mathrm{i}}$ only if previous classifiers are not confident
$\square$ Good with high precision/ low recall classifiers


## Ensemble methods

Boosting$\square$ Weighted training sets

- Ex: AdaboostBagging
- Resampled training sets
$\square$ Ex: Random forests
Cascading
$\square$ Ordered collection of classifiers

